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Experimental characterisation of the magnetic field correction factor, $\kappa_{\rightarrow B}$, for Roos chambers in a parallel MRI-linac

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3 **Title: Experimental characterisation of the magnetic field correction factor, $k_{\vec{B}}$, for Roos chambers**
4
5 **in a parallel MRI-linac**
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7

8
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11 absorbed dose, magnetic field, MRgRT, MRI-linacs, Roos Chamber
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14
15 **5 Authors:**

16
17 Jarrad Begg¹⁻³, Urszula Jelen², Paul Keall^{2,4}, Gary Liney^{1,2,3,5}, Lois Holloway¹⁻⁶
18
19

20
21 ¹Department of Medical Physics, Liverpool and Macarthur Cancer Therapy Centre, Liverpool, NSW,
22
23 2170, Australia
24

25
26 ²Ingham Institute for Applied Medical Research, Liverpool, NSW, 2170, Australia
27

28 **10** ³South Western Sydney Clinical School, University of New South Wales, Liverpool, NSW, 2170,
29
30 Australia
31

32
33 ⁴Faculty of Medicine and Health, University of Sydney, Camperdown, NSW, 2505, Australia
34

35
36 ⁵Centre for Medical Radiation Physics, University of Wollongong, Wollongong, New South Wales
37
38 (NSW), 2522, Australia

39 **15** ⁶Institute of Medical Physics, University of Sydney, Camperdown, NSW, 2505, Australia
40

41 **Corresponding Author Email:**

42
43
44 jarrad.begg@health.nsw.gov.au
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Abstract:*Objective*

Reference dosimetry on an MRI-linac requires a chamber specific magnetic field correction factor, $k_{\vec{B}}$. This work aims to measure the correction factor for a parallel plate chamber on a parallel MRI-linac.

Approach

$k_{\vec{B}}$ is defined as the ratio of the absorbed dose to water calibration coefficient in the presence of the magnetic field, $N_{D,w}^{\vec{B}}$ relative to that under 0 T conditions, $N_{D,w}^{0T}$. $k_{\vec{B}}$ was measured via a $N_{D,w}$ transfer to a field chamber at each magnetic field strength from a chamber with known $N_{D,w}$ and $k_{\vec{B}}$. This was achieved on the parallel MRI-linac by moving the measurement set-up between a high magnetic field strength region at the MRI-isocentre and a low magnetic field strength region at the end of the bore whilst maintaining consistent set-up and scatter conditions. Three PTW 34001 Roos chambers were investigated as well as a PTW 30013 Farmer used to validate methodology.

Main Results

The beam quality used for the measurements of $k_{\vec{B}}$ was $TPR_{20/10} = 0.632$. The $k_{\vec{B}}$ for the PTW Farmer chamber at 1 T on a parallel MRI-linac was 0.993 ± 0.013 ($k = 1$). The average $k_{\vec{B}}$ factor measured for the three Roos chambers on a 1 T parallel MRI-linac was 0.999 ± 0.014 ($k = 1$).

Significance

The results presented are the first measurements of $k_{\vec{B}}$ for a Roos chamber on a parallel MRI-linac. The Roos chamber results demonstrate the potential for the chamber as a reference dosimeter in parallel MRI-linacs.

Introduction

MRI-linacs have been developed with the radiation field aligned perpendicular to the main magnetic field (B_0) (Lagendijk *et al.*, 2014; Mutic and Dempsey, 2014), and with the radiation field aligned parallel to the B_0 field (Keall *et al.*, 2014; Fallone, 2014). The Lorentz force has the potential to impact the dose deposition of both systems. For perpendicular MRI-linacs the electrons depositing dose are more likely to scatter laterally and slightly shallower relative to conventional linacs causing a lateral shift in the dose deposition (Raaijmakers *et al.*, 2008). Electrons depositing dose on parallel MRI-linacs are more likely to be forward scattered and only the vector component of the electron that is perpendicular to the magnetic field is affected causing no change in dose deposition provided charged particle equilibrium is maintained (Bielajew, 1993).

The magnetic field has previously been shown to impact dosimetry measurements due to changes in the pathlength of electrons across the chamber (Meijsing *et al.*, 2009). Dosimetry measurements on conventional linacs are traceable to primary standards laboratories. A similar traceability is required for MRI-linacs in order to ensure accuracy of the dose being delivered to patients. Therefore, accurate magnetic field correction factors, accounting for the change in dose deposition and chamber response, are required in order to accurately measure dose.

Magnetic field correction factors have been shown to depend on chamber size (Spindeldreier *et al.*, 2017) and orientation between the chamber, magnetic field and radiation field (O'Brien *et al.*, 2016; Malkov and Rogers, 2018; Reynolds *et al.*, 2013; Reynolds *et al.*, 2017; Meijsing *et al.*, 2009; Smit *et al.*, 2013). The different MRI-linac designs have different radiation beam qualities, magnetic field strengths and orientations making chamber corrections specific to a system. For perpendicular MRI-linacs, the magnetic field causes a lateral shift of the electrons inside the sensitive volume. The lateral shift in the electrons not only changes the number of ionisation events detected in the sensitive volume, but can also cause electrons that would have deposited dose inside the sensitive volume to deposit dose inside the dead volume of the ionisation chamber or alternatively, cause electrons that

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3 would not have deposited dose inside the sensitive volume to be deflected into the sensitive volume
4
5 (Pojtinger *et al.*, 2019). For parallel MRI-linacs, electrons in air material have been shown to reduce
6
7 lateral scatter and increase pathlength parallel to the central axis (Gargett *et al.*, 2015). Minor changes
8 65 lateral scatter and increase pathlength parallel to the central axis (Gargett *et al.*, 2015). Minor changes
9
10 in the dose distribution inside a cylindrical chamber have been simulated (Spindeldreier *et al.*, 2017).
11
12 Therefore, only small changes in the charge collected inside the sensitive volume of an ion chamber
13
14 are expected due to the magnetic field.
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16

17 Chamber correction factors have been simulated for Farmer-type chambers with corrections in the
18
19 order of 1 % for parallel MRI-linacs (Spindeldreier *et al.*, 2017; Malkov and Rogers, 2018). Previous
20 70 order of 1 % for parallel MRI-linacs (Spindeldreier *et al.*, 2017; Malkov and Rogers, 2018). Previous
21
22 Monte Carlo simulations of correction factors for parallel plate chambers for perpendicular MRI-linacs
23
24 have been up to 9 % dependent on magnetic field strength and chamber type (Pojtinger *et al.*, 2018;
25
26 Malkov and Rogers, 2018). For parallel MRI-linacs, prior simulations have shown correction factors in
27
28 the order of 1.5 % (Malkov and Rogers, 2018). No measurements of parallel plate correction factors
29
30 have been presented in the literature and thus no verification of the Monte Carlo simulations. The aim
31 75 have been presented in the literature and thus no verification of the Monte Carlo simulations. The aim
32
33 of this work was to measure the correction factor for a parallel plate type chamber on a high field
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35 parallel MRI-linac.
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38 **Methods**

39 *The Australian MRI-Linac*

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44 80 The Australian MRI-linac consists of a Varian Linatron (Varian Medical Systems, Inc, USA) radiation
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46 source aligned parallel to the primary magnetic field, B_0 , of a bespoke 1 T split bore magnet (Agilent
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48 Technologies Inc. USA). The radiation source is decoupled from the magnet allowing the radiation
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50 source to MRI isocentre distance to change (Jelen *et al.*, 2020). The radiation beam is a flattening filter
51
52 free (FFF) beam with a beam quality of $TPR_{20/10} = 0.632$ (Begg *et al.*, 2019). The magnet design
53
54 incorporates a low field strength region at the end of the MRI bore (Whelan *et al.*, 2018; Roberts *et*
55 85 incorporates a low field strength region at the end of the MRI bore (Whelan *et al.*, 2018; Roberts *et*
56
57 *al.*, 2019).
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Magnetic field correction factor formalism

The magnetic field impacts both the dose distribution and the pathlength of electrons through dosimeters, which effects the collected charge. Examples of the change in the dose distribution for perpendicular and parallel fields have been described by Raaijmakers *et al.* (Raaijmakers *et al.*, 2008) and Bielajew (Bielajew, 1993) respectively. Examples of changing electron path lengths through ion chamber cavities has been shown by Meijnsing *et al.* (Meijnsing *et al.*, 2009).

Dose to water is measured via the charge collected in the dosimeter, corrected for influence quantities, dosimeter calibration factor and beam quality correction factor as shown in equation 1.

$D_{w,Q}$ is the dose to water at a certain beam quality, Q . M_Q is the measured charge at the beam quality Q correct for influence factors such as temperature, pressure, polarity and recombination. N_{D,w,Q_0} is the dosimeter calibration factor at the reference beam quality, Q_0 . k_{Q,Q_0} is the correction between the reference and measured beam quality.

$$D_{w,Q} = M_Q N_{D,w,Q_0} k_{Q,Q_0} \quad (1)$$

The magnetic field correction factor, $k_{\vec{B}}$, is used during reference dosimetry in a magnetic field to correct for the change in the pathlength of electrons through a detector which affects the measured charge of the detector. The correction factor is the ratio of the dose to water calibration coefficient at the magnetic field strength, $N_{D,w,Field}^{\vec{B}}$, relative to no magnetic field, $N_{D,w,Field}^{0T}$, at the same beam quality (see equation 2). The correction factor is dependent on the orientation of the chamber, radiation beam and magnetic field, as well as the machine specific reference conditions. Following the nomenclature established by de Pooter *et al.* (de Pooter *et al.*, 2020), the notation $k_{\vec{B}}$ is used in this work. The notation for beam quality, Q , has been removed as the work was completed at the one beam quality.

$$k_{\vec{B}} = \frac{N_{D,wField}^{\vec{B}}}{N_{D,wField}^{OT}} \quad (2)$$

110 This study measures the $N_{D,wField}^{\vec{B}}$ and $N_{D,wField}^{OT}$ for field chambers via cross-calibration from a detector with known $N_{D,w}$ values at both magnetic field strengths. From this, the $k_{\vec{B}}$ for each chamber was determined.

115 The dose to water calibration coefficient at each field strength can be broken down into the ratio of the dose to water divided by the measured charge of the chamber. The magnetic field correction factor corrects the response of the detector for the influence of the magnetic field. The magnetic field can affect the detector by changing both the path of the electrons in detector and by changing the electron fluence in the medium around the detector (O'Brien *et al.*, 2016; van Asselen *et al.*, 2018). Dose deposition changes in water are essential to consider when determining the magnetic field correction factor by means of the method applied in the current study. For a parallel orientation MRI-
 120 linac, previous simulations (Bielajew, 1993; Oborn *et al.*, 2016) and measurements (Begg *et al.*, 2019) have shown no difference in the absorbed dose at the measurement point. Bielajew (Bielajew, 1993) showed via simulations and mathematical proofs that, provided lateral scatter equilibrium was established, the dose deposited to a point is independent of the magnetic field strength in parallel systems. Therefore the magnetic field influence on dose deposition on parallel MRI-linacs does not
 125 need to be considered in the current study. For perpendicular orientation MRI-linacs, the curved path of the electrons due to the magnetic field, causes the energy from a photon interaction point to be deposited, on average, closer to the interaction point. This reduces the absorbed dose at the measurement point by $\sim 0.5\%$ in a $10\text{ cm} \times 10\text{ cm}$ field at 1.5 T (van Asselen *et al.*, 2018; O'Brien *et al.*, 2016). The measurements presented in this work only considers the parallel geometry.

130 *Magnetic field correction factor measurement overview*

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3 Current available methods of measuring chamber correction factors involve building specific
4 calorimeters for use in magnetic fields (de Prez *et al.*, 2019), alanine dosimetry (Billas *et al.*, 2017) or
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6 measuring output during ramp-down and ramp-up states of the magnet (Smit *et al.*, 2013; van Asselen
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13 135 *et al.*, 2016; Spindeldreier *et al.*, 2017; Malkov and Rogers, 2018; Reynolds *et al.*, 2013; Poytinger *et al.*,
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15 2018; Meijnsing *et al.*, 2009). Detectors require measurements at both high and low field strengths to
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17 directly measure magnetic field correction factors. This leaves two options: 1) A monitor dependent
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19 method where the magnet is ramped up and down for measurements at a 0 T and high field strength
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21 (van Asselen *et al.*, 2018; Smit *et al.*, 2013), or 2) Move the measurement set-up between the high
22
23 140 and low magnetic field strength regions so that measurements are acquired with the chamber at each
24
25 field region whilst maintaining irradiation conditions such as consistent field size, detector depth and
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27 source to surface distance. The decoupled nature of the radiation source and magnet on the Australian
28
29 MRI-linac allows the second approach to be applied in this work.
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33 The monitor dependent method, used by van Asselen *et al.* (van Asselen *et al.*, 2018) to determine $k_{\bar{B}}$,
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35 145 separates the magnetic field effects on dose deposition and detector response. The dose deposition
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37 difference was assessed via Monte Carlo simulations and detector response via the ramping up and
38
39 down of the magnetic field. Our method for determining $k_{\bar{B}}$ combines the difference in dose
40
41 deposition and detector response into the $N_{D,w}$ transfer at each field strength.
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45 The $k_{\bar{B}}$ was measured via a cross calibration of the absorbed dose to water calibration coefficient, $N_{D,w}$
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47 150 , between a reference and field chamber, in both the high and low magnetic field set-ups on the
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49 Australian MRI-linac to obtain the factors required for the field chamber in equation 1. The reference
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51 chamber used in this work was previously calibrated by the National Physics Laboratory (NPL,
52
53 Teddington, UK) at 0 T via a conventional calibration and at 1 T via Alanine (Billas *et al.*, 2018).
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55 Therefore in the high and low magnetic field set-ups the appropriate $N_{D,w}$ was transferred. The
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58 155 reference chamber was a Scanditronix Wellhofer FC65-G (IBA Dosimetry GmbH, Schwarzenbruck,
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Germany). The separate 0 T and 1 T $N_{D,w}$ calibration of this chamber results in a $k_{\vec{B}}$ of 0.990 ± 0.012 on the Australian MRI-linac using equation **Error! Reference source not found.**. This value agrees well with the previously simulated value of 0.9914 ± 0.001 which was for a parallel 7 MV photon beam and a 1.5 T magnetic field (Malkov and Rogers, 2018).

160 Figure 1A shows the measurement set-up for a Roos chamber (PTW-Freiburg GmbH, Freiburg, Germany) at the low magnetic strength field region at the end of the magnet bore. Figure 1B shows a diagram of the low and high field measurement set-ups highlighting the consistent source to chamber distance maintained between the two set-ups. A $N_{D,w}$ transfer was used for the measurements in the low and high field region due to the output of the linatron changing with source to MRI-isocentre distance due to the impact of the fringe field (Jelen *et al.*, 2020).

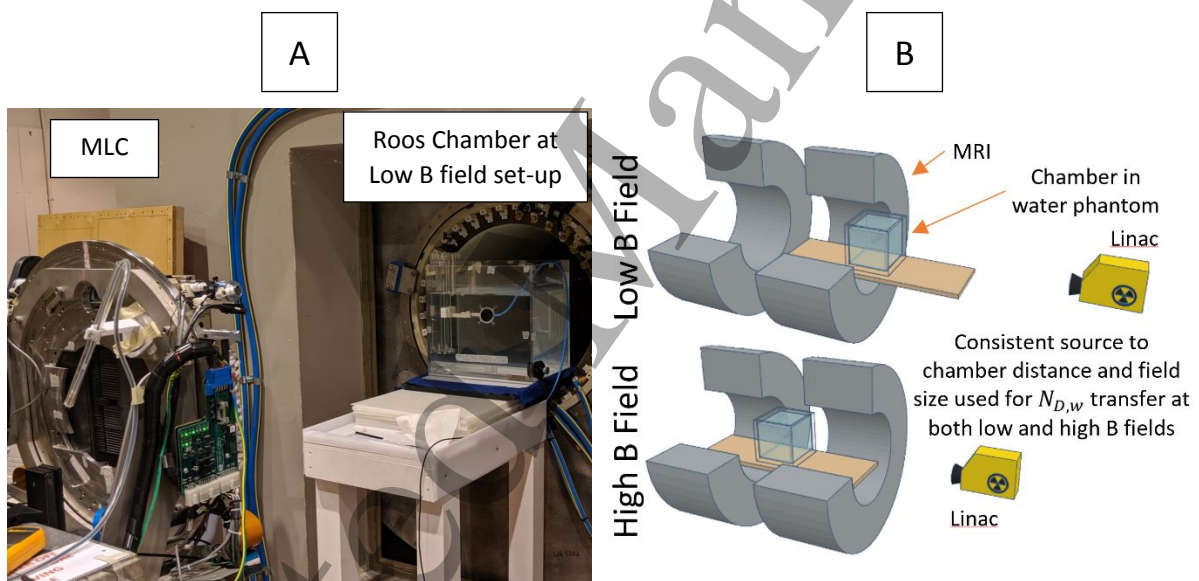


Figure 1: A) A Roos chamber set-up at the low magnetic field strength region. B) Diagram of the chamber, linac and MRI for both the low and high field measurement set-ups. The measurement set-up was transferred between the low and high field region maintaining consistent source to chamber distances and field sizes.

170 The method used to measure $k_{\vec{B}}$ requires the low field region at the end of the bore to be identified so that consistent conditions can be maintained between the high and low field set-ups. The method was validated by measurement of the correction factor for a second Farmer-type chamber which could

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3 be compared to published factors from the literature. Once validated, $k_{\bar{B}}$ for three Roos chambers
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5 were measured and compared to the literature. Three Roos chambers were measured in this work to
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8 175 investigate agreement between the chambers.

9 10 *Detectors*

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13 The Farmer-type chambers were a Scanditronix Wellhofer FC65-G (s/n: 819) and a PTW 30013 0.6cc
14
15 (s/n: 10066). The FC65-G was used as the reference as a calibration traceable to the NPL had been
16
17 established. The reference point of the Farmer-type chambers (central axis) was set up at 10 cm depth
18
19
20 180 in water.

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23 The magnetic field correction factor was measured for three PTW 34001 Roos chambers (s/n: 473,
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25 1394 and 2957). The inside surface of the entrance window of the Roos chambers was set up at 10 cm
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27 depth in water.

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30 A CC13 chamber (s/n: 15996, IBA Dosimetry GmbH) was set up as an external monitor chamber
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33 185 between the source and MLC to correct for variations in linac output within repeat measurements.
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35 The external monitor chamber was used to correct linac output between different chambers at each
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37 magnetic field but was not used to correct output between magnetic field strengths as this
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39 independent monitor would be subject to changing magnetic field conditions as the linac was moved
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41 between the low and high field measurement set-ups.

42 43 44 190 *Low B Field Location for chamber measurements*

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47 Simulations of the magnetic field map for the MRI used as part of the Australian MRI-Linac, showing
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49 both the low and high magnetic field strength positions, have been presented by Whelan *et al.*
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51 (Whelan *et al.*, 2018) and Roberts *et al.* (Roberts *et al.*, 2019). Previous measurements of the magnetic
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53 field near the low magnetic field point have shown magnetic field strengths less than 0.05 T. To
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56 195 identify the position of the minimum magnetic field strength, and therefore the optimal location for
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58 the placement of the chamber, as well as evaluate uncertainties associated with incorrect positioning
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3 of the detectors at the low field region, the magnitude of the magnetic field strength position was
4 mapped in a 2D plane at isocentre height from the isocentre out to a distance of 250 cm towards the
5 radiation source. A single direction HGM09s Gaussmeter (MAGSYS, Germany, s/n: 011215007) was
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10 200 used in the MRI-linac bore and a Vector/Magnitude 140 Gaussmeter Model VGM (s/n: 568, AlphaLab
11
12 Inc, Utah, USA) outside the bore.

15 *Measurements of $k_{\vec{B}}$*

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18 The $k_{\vec{B}}$ for all chambers was calculated based on the average of the $k_{\vec{B}}$ measured for each chamber in
19 three separate transfer sessions. A singular transfer session consisted of transferring the dose to water
20 calibration coefficient, at both magnetic field strengths, from the FC65-G chamber to the new
21
22 205 chamber (either the PTW Farmer or one of the three Roos chambers). Polarity and recombination
23 were measured for each chamber at both magnetic field strengths. Measured charge for each
24 chamber was corrected for temperature, pressure, polarity and recombination via established
25 methods (Andreo *et al.*, 2001). The transfer session was repeated three times on separate days to
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33 210 investigate set-up reproducibility and the stability of polarity, recombination and $k_{\vec{B}}$. Measured
34 transfers of the dose to water calibration coefficient at each magnetic field were assessed for
35 reproducibility over the three separate measurements. The average dose to water calibration
36 coefficient for each magnetic field strength was then used in equation 1 to calculate the magnetic field
37 correction factor, $k_{\vec{B}}$. An uncertainty budget for the measurement of $k_{\vec{B}}$ is detailed below.

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45 215 Recombination and polarity were measured at the low and high magnetic field strength set-ups to
46 determine if the magnetic field would influence chamber characteristics. Jaffe plots, over a voltage
47 range of 50 V – 300 V for the Farmer-type and 25 V – 150 V for the Roos chambers, were used to
48 compare the charge collected and the applied polarity voltage to determine if the magnetic field had
49 an impact on the suitability of the applied voltage range for determining recombination via the two
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57 220 voltage method.

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3 The measured $k_{\bar{B}}$ for the PTW Farmer was compared to simulations from Malkov and Rogers (Malkov
4 and Rogers, 2018) and Spindeldreier *et al.* (Spindeldreier *et al.*, 2017) in order to validate the proposed
5 measurement methodology.
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10 *Rotational Response of the Roos Chamber*

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13 225 Rotations of the front face of the Roos chamber away from perpendicular to the beam central axis
14 were measured at both field strengths to investigate the impact of angular set-up uncertainties on $k_{\bar{B}}$.
15
16 0° angle was defined as the front face of the Roos chamber perpendicular to the beam/magnetic field
17 direction. Angular response measurements consisted of the following at both the low and high field:
18
19 2) Chamber response readings
20
21 1) An initial chamber response with the chamber set-up at a 0° angle, 2) Chamber response readings
22
23 at 10 degree intervals in a positive or clockwise rotation to + 30°, 3) Repeat chamber response
24
25 230 measurement at 0° angle, 4) Chamber response readings at 10 degree intervals in a negative or
26
27 counter-clockwise rotation to - 30°, 5) Repeat chamber response measurement at 0° angle. The
28
29 response at each angle was calculated relative to the average response at 0° for each magnetic field
30
31 strength. The difference between low and high magnetic field responses at the same angle were
32
33 compared. Three repeat angular response data sets were acquired for the Roos chamber with serial
34
35 number 2957 to assess reproducibility.
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41 *Calculation of Uncertainties*

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44 The uncertainty of $k_{\bar{B}}$ measured via a $N_{D,w}$ transfer at both low and high field strength was calculated
45
46 via a full uncertainty budget (JCGM, 2008). First the combined relative standard uncertainty of the
47
48 240 $N_{D,w}$ transfer for both the PTW Farmer chamber and Roos chamber at both 0 T and 1 T was evaluated.
49
50 Second, the combined relative standard uncertainty of the transferred $N_{D,w}$ at each magnetic field
51
52 strength was then used to calculate the combined relative standard uncertainty in $k_{\bar{B}}$ for each
53
54 chamber (Table 1). A Type A interday reproducibility of the measured $k_{\bar{B}}$ was also included in the
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56 combined relative standard uncertainty. For both Farmer-type and Roos chambers the combined
57
58 relative standard uncertainty in the measured $k_{\bar{B}}$ was 1.6 % ($k = 1$).
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3 Considered in the combined relative standard uncertainty of the $N_{D,w}$ transfer were the reproducibility
4
5 of the reference and field chambers, uncertainty in the $N_{D,w}$ value from the NPL, positioning of the
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7 reference and field chamber at the correct depth, water tank set-up distance, stability of the reference
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9 chamber over time and uncertainty in the influence quantities (temperature, pressure, polarity,
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11 recombination and leakage). Differences in the radial profile between the two Farmer-type chambers
12
13 250 were not considered as the cross-section of the chamber is of approximately the same size.
14
15 Differences in the radial profile between the Roos chamber and the Farmer-type reference chamber
16
17 were evaluated via calculation of the non-uniformity correction along both the long and lateral axes
18
19 of the Farmer-type chamber and the corresponding axes for the Roos chamber. An estimation in the
20
21 uncertainty due to differences in volume averaging between the Farmer-type and Roos chambers was
22
23 255 given based on the observed differences in the non-uniformity correction. Differences in the non-
24
25 uniformity correction were observed to be small due to the extended set-up distance of the FFF beam
26
27 minimising differences in the radial profile. Measurements in this work show that rotations of the
28
29 Roos chamber of greater than 10° are required to impact the measured charge. Set-up of the Roos
30
31 chamber restricted rotations to $1^\circ - 2^\circ$. Therefore, rotational positional uncertainty of the Roos
32
33 260 chamber was considered negligible and not included in the uncertainty budget. Details on the
34
35 chamber was considered negligible and not included in the uncertainty budget. Details on the
36
37 combined relative standard uncertainty of the $N_{D,w}$ transfer are described in appendix table 1.
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41

42 *Table 1: Combined relative standard uncertainty of the $N_{D,w}$ transfer at both 0 T and 1 T for the PTW*
43 *Farmer and Roos chambers.*

48 <i>Component of Uncertainty</i>	PTW Farmer (%)	Roos (%)
50 <i>Type A</i>		
51 Interday Reproducibility of $k_{\bar{B}}$ for each chamber	0.04	0.2
55 <i>Type B</i>		
56 Uncertainty in $N_{D,w,Q}$ for chamber at 0 T (see Appendix Table 57 1Error! Reference source not found.)	0.8	0.85

Uncertainty in $N_{D,w,Q}$ for chamber at 1 T (see Appendix Table 1 Error! Reference source not found.)	1.1	1.1
Combined Relative Standard Uncertainty ($k = 1$)	1.34 %	1.4 %
Expanded Uncertainty ($k = 2$)	2.7 %	2.8 %

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Results

Low B Field Location for chamber measurements

The minimal B field location identified for optimal chamber position at the low magnetic field region was measured to be 0.001 T in magnitude at a distance from the MRI isocentre of 129 cm. The magnitude of the magnetic field was less than 0.007 T in volume of 1 cm radius surrounding the low magnetic region.

Measurements of $k_{\vec{B}}$

Measurements of the recombination and polarity were within 0.2 % of unity for the FC65-G and PTW Farmer chambers and 0.3 % of unity for the Roos chambers with no difference between the magnetic fields observed. Jaffe plots, for both the Farmer-type chambers and the Roos chambers, show collected charge following a linear trend over the range of voltages applied. Repeat measurements of the transferred dose to water calibration coefficient for the PTW Farmer were within 0.1 % of the average value at the low and high magnetic field strength respectively. Repeat measurements of the transferred dose to water calibration coefficients for the three Roos chambers were within 0.3 % of the average value at both magnetic field strengths.

The average $k_{\vec{B}}$ for the PTW Farmer chamber was 0.993 ± 0.013 ($k = 1$). Uncertainty was calculated as per table 1. The measured magnetic field correction factor for each transfer session was within 0.1 % of the average correction factor measured from 3 repeat transfer sessions for the PTW Farmer chamber.

285 The dose to water calibration coefficients measured for two Roos chambers (s/n: 1394 and 2957) were
 in good agreement with each other for each magnetic field strength. Roos chamber s/n: 473 was
 systematically 2.5 % – 3 % higher relative to the measured coefficients for Roos chambers with serial
 numbers 1394 and 2957.

The average measured $k_{\bar{B}}$ for all three Roos chambers was 0.999 ± 0.014 ($k = 1$). Uncertainty was
 290 calculated as per table 1. Figure 2 shows the measured magnetic field correction factor for each
 transfer session, for all three chambers, was within 0.2 % of the average correction factor.

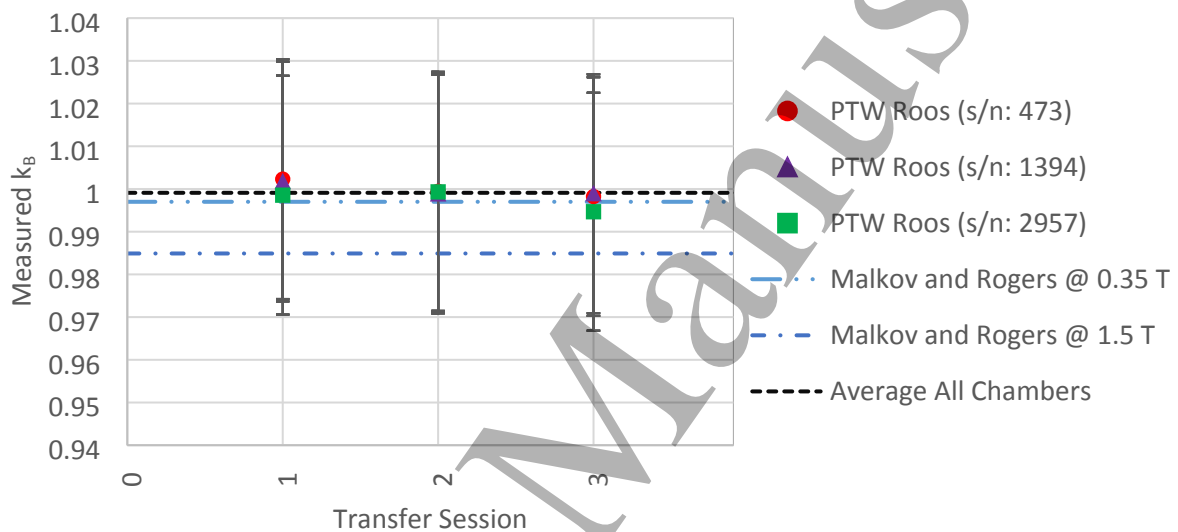


Figure 2: Measured $k_{\bar{B}}$ for the three Roos chambers for the three measurements. The average $k_{\bar{B}}$
 over all chambers was 0.999 ± 0.014 ($k = 1$). $k_{\bar{B}}$ was measured for a parallel MRI-linac at a beam quality
 of $TPR_{20/10} = 0.632$. Uncertainty was calculated as per table 1. Error bars around individual $k_{\bar{B}}$
 295 measurements are 95 % confidence intervals ($k = 2$). The results show agreement with previously
 published data from Malkov and Rogers (Malkov and Rogers, 2018).

Rotational Response of the Roos Chamber

The response of the three Roos chambers with varying rotational tilt is shown in figure 3.
 300 Reproducibility of the chamber response at 0° across the 3 chambers was within $\pm 0.16\%$ at both field
 strengths. The average response of the Roos chamber with a $\pm 10^\circ$ face tilt was less than $\pm 0.2\%$

different relative to the response measured with a 0° face tilt at both field strengths. An outlier of -0.22 % difference relative to 0° was observed for the Roos 473 at an angle of -10° . The response at high field strengths for non 0° angles relative to the 0° angle was within 0.2 % of the low field strength response for the corresponding angle between $\pm 30^\circ$.

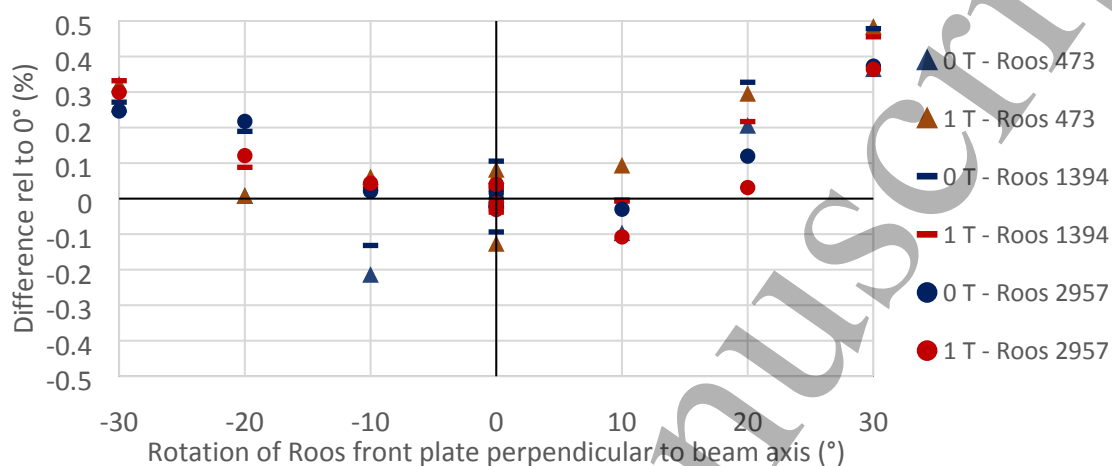


Figure 3: Measured response of the three Roos chambers at different angular rotations relative to an average 0° response

Discussion

In this work we experimentally validated a method for measuring $k_{\vec{B}}$ and then applied the method to characterise $k_{\vec{B}}$ for three Roos chambers. The experimentally measured $k_{\vec{B}}$ for a PTW Farmer and Roos chamber was 0.993 ± 0.013 ($k = 1$) and 0.999 ± 0.014 ($k = 1$) respectively for a parallel MRI-linac at a beam quality of $TPR_{20/10} = 0.632$. Uncertainty was calculated as per table 1. Potential reasons for the large uncertainty and comparisons to previously published literature are discussed below.

Low B Field Location for chamber measurements

The minimal B field location had a field strength of 0.001 T. Positionally, the chamber can be set up within a 1 cm sphere at this point and be below 0.007 T. Our measurements are consistent with previously published simulations of the magnetic field for this magnet (Kolling *et al.*, 2013; Whelan *et al.*, 2018). If we can assume chamber response in the magnetic field is approximately linear relative

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3 320 to field strength, as shown for Farmer-type chambers by Reynolds *et al.* (Reynolds *et al.*, 2013), then
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5 the difference between 0 T and 0.001 T is insignificant compared to the difference between 0.001 T
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7 and 1 T, which is the field strength at the isocentre of the MRI. Using the 0.001 T location to set-up a
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9 low field measurement point is a good approximation of 0 T and therefore will have minimal impact
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11 on chamber response when measuring $k_{\vec{B}}$. Positional changes within assumed set-up uncertainties, in
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14 325 both the low and high measurement set-ups, will have minimal impact on the magnitude of the
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16 magnetic field at each position and therefore the collected charge.
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19 *Measurements of $k_{\vec{B}}$*

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22 Recombination and polarity measured for all chambers did not show any difference between the two
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24 magnetic field strengths. Jaffe plots over voltage ranges of 50 V – 300 V for the Farmer-type and 25 V
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26 – 150 V for the Roos chambers confirm the applicability of the two-voltage method for measuring
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28 recombination at both low and high field strengths. This is consistent with previous measurements of
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30 ion recombination of a cylindrical chamber in a perpendicular MRI-linac, which was observed to have
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32 no significant change in ion recombination due to the magnetic field over a voltage range between 25
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34 V – 400 V (Smit *et al.*, 2013).
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39 335 The uncertainty calculated for $k_{\vec{B}}$ via table 1 is large compared to Monte Carlo simulations. This is
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41 primarily due to the large uncertainty in $N_{D,w,Q}^{Ref}$ for the reference chamber used at both 0 T and 1 T.
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43 The reproducibility of measurements, for both the reference chamber and field chamber, and
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45 reproducibility of the reference chamber contribute large relative uncertainties to the overall
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47 combined uncertainty. Because the measurements are at both 0 T and 1 T, the combined relative
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49 uncertainty for the calculation of $k_{\vec{B}}$ is large. The quoted Type A uncertainty in $k_{\vec{B}}$ comes from the
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51 reproducibility of the three transfer sessions. Using this method to determine $k_{\vec{B}}$ for absorbed dose
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53 measurements will introduce large uncertainties in the measured dose.
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58 The $k_{\vec{B}}$ measured for the PTW Farmer chamber in our work, 0.993 ± 0.013 ($k = 1$), showed good
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60 agreement with published Monte Carlo simulations in a parallel MRI-linac (Malkov and Rogers, 2018;

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3 345 Spindeldreier *et al.*, 2017). Malkov and Rogers (Malkov and Rogers, 2018) simulated a $k_{\bar{B}}$ value of
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5 0.9937 \pm 0.0010 using a 1.5 T magnetic field and a 7 MV MRgRT photon spectrum ($TPR_{20,10} = 0.695$)
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7 from the Elekta Unity (Elekta Solutions AB, Stockholm, Sweden). Spindeldreier *et al.* (Spindeldreier *et*
8
9 *al.*, 2017) simulated a $k_{\bar{B}}$ value of 0.994 \pm 0.003 using a 1.0 T magnetic field and a beam quality of
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11 $TPR_{20,10}$ equal to 0.674. Previous measurements of the energy spectrum on the Australian MRI-linac
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13 350 show a $TPR_{20,10}$ value of 0.632 \pm 0.007 (Begg *et al.*, 2019). Increased magnetic field strength results in
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15 a larger $k_{\bar{B}}$ factor. (Spindeldreier *et al.*, 2017). Differences in beam quality have been shown to
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17 introduce up to 0.5 % variation in $k_{\bar{B}}$ factors for cylindrical chambers on parallel MRI-linacs with lower
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19 energy beams being impacted by the magnetic field to a larger extent (Malkov and Rogers, 2018). The
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21 differences in simulated spectrums and magnetic field strengths highlight the need to verify simulated
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23 values with measurements.
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28 The measured $k_{\bar{B}}$ for the Roos chamber was similar to previously published Monte Carlo simulated
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30 values at 0.35 T and 1.5 T (Malkov and Rogers, 2018). The Type A uncertainty in the average $k_{\bar{B}}$ value
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32 of 0.2 % ($k = 1$) was no greater than the Type A uncertainty in the measured $k_{\bar{B}}$ for each individual
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34 Roos chamber. The agreement in $k_{\bar{B}}$ observed across all Roos chambers is similar to the agreement in
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36 $k_{\bar{B}}$ observed for Farmer-type chambers (Woodings *et al.*, 2019). Previous simulations of the Roos
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38 360 chamber calculated a $k_{\bar{B}}$ correction factor of 0.9849 \pm 0.001 using a 1.5 T magnetic field and beam
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40 quality of $TPR_{20,10} = 0.695$, and 0.997 \pm 0.001 using a 0.35 T magnetic field and beam quality of $TPR_{20,10}$
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42 = 0.568 (Malkov and Rogers, 2018). Our measurement, 0.999 \pm 0.014 ($k = 1$), agrees with the lower
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44 beam quality and magnetic field strength simulation and is within 95 % confidence intervals for the
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46 higher beam quality and field strength. Differences in magnetic field strength and beam energy have
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48 365 an impact on the measured correction factor. As the magnetic field strength increases, the radius of
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50 curvature of an electron in a magnetic field decreases meaning the air gap between the parallel plates
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52 of the Roos chamber increases in significance as the field strength increases. Without further
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54 simulations and/or measurements at different magnetic field strengths, the relationship between $k_{\bar{B}}$
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3 370 and magnetic field is unknown. A correction factor close to 1.0 is expected for the Roos chamber
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5 because the predominately forward scattered electrons only have a small perpendicular component
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7 relative to the magnetic field. The stem material has been shown to impact $k_{\vec{B}}$ for cylindrical chambers
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9 (Malkov and Rogers, 2018). Finite element modelling of electrical fields inside the chamber has shown
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11 the impact of dead volumes on $k_{\vec{B}}$ for a cylindrical chamber (Pojtinger *et al.*, 2019). Further
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13 375 simulations and modelling are required to investigate the impact of materials, the sensitive volume
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15 and the impact of the guard ring for parallel plate chambers in magnetic fields.
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19 The methodology presented is similar to the ramp up/down method presented by Smit *et al.* (Smit *et*
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21 *al.*, 2013) and van Asselen *et al.* (van Asselen *et al.*, 2018). Our method has replaced the ramping up
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23 and down of the magnet with the ability to move the linac and dosimeter from a high to low field
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25 380 measurement set-up. To the best of the authors' knowledge, no other MRI-linacs have the ability to
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27 move the linac from a high field to low field set-up.
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31 Previous simulations of the magnetic field correction factor for a Roos chamber in perpendicular MRI-
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33 linacs have shown correction factors of between 8% – 9% (Pojtinger *et al.*, 2018; Malkov and Rogers,
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35 2018). These simulated values, and an understanding of the electron paths for a wide air cavity such
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37 385 as a parallel plate chamber, show the unsuitability of Roos chambers for absorbed dose determination
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39 in perpendicular MRI-linacs.
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42 43 *Rotational Response of the Roos Chamber*

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45 Reproducibility of the chamber response at 0°, for both the low and high field, was within $\pm 0.16\%$.
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47 This places a limit on the ability to distinguish between response differences due to reproducibility or
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49 390 chamber tilt. The response at an angle of $\pm 10^\circ$ for both field strengths was consistent with the
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51 manufacturer recommendations for directional response ($< 0.1\%$ for a $\pm 10^\circ$ rotation (PTW, 2020))
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53 noting the manufacturer recommendations were not in a magnetic field. The -0.22% difference
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55 relative to the average 0° value for the Roos 473 at -10° was not thought to be significant. This is due
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57 to the relatively large tilt (10°) applied to the chamber which was easily observable as a set-up error.
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3 395 The agreement between low and high field strengths within 0.2 % indicates that between face tilt
4 angles of $\pm 30^\circ$ there is no difference in the response caused by the magnetic field. This indicates that
5 the magnetic field does not make the Roos chamber more susceptible to tilt set-up uncertainties. The
6 measurements presented are in agreement with published simulations where no difference in the
7 cavity dose to air was observed for parallel plate chambers with face tilts up to 3° relative to
8 simulations with no chamber tilt, in a parallel radiation and magnetic field (Malkov and Rogers, 2018).
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17 *Limitations and Future Work*

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20 The method used for measuring chamber correction factors relied on a cross-calibration from a
21 chamber with a known dose to water calibration coefficient at both magnetic field strengths. This
22 requires the chamber with the known magnetic field correction factor to have either been calibrated
23 in the magnetic field by comparison to a dosimeter with a known output in the magnetic field (alanine
24 dosimetry (Billas *et al.*, 2017) or calorimetry (de Prez *et al.*, 2019)) or the chambers correction factor
25 having been calculated via measurements with the magnetic field in a ramped up and down state
26 (Smit *et al.*, 2013; van Asselen *et al.*, 2018). Future work will aim to develop an independent method
27 to determine magnetic field calibration factors that does not depend on prior chamber calibration
28 factors.
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41 An alternative method for determining $k_{\vec{B}}$, using similar measurements to those presented in this
42 work, would be to transfer $k_{\vec{B}}$ from a chamber with a known $k_{\vec{B}}$ instead of using known $N_{D,w}$ values at
43 both magnetic field strengths as presented in this work. If the known $k_{\vec{B}}$ was measured via a primary
44 standard with a small uncertainty, then this could potentially reduce the uncertainty in the transferred
45 $k_{\vec{B}}$ depending on the uncertainty in the known $k_{\vec{B}}$. The additional uncertainty for long term chamber
46 stability could be removed from the uncertainty budget. For the measurements presented, $k_{\vec{B}}$ would
47 be calculated from the ratio of the $N_{D,w}$ values at both magnetic field strengths and thus no reduction
48 in uncertainty would be achieved.
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3 Parallel plate type chambers have not been previously recommended for photon beam reference
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5 420 dosimetry in dosimetry protocols (Andreo *et al.*, 2001). Recent measurements and simulations of the
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7 absorbed dose calibration factor with parallel plate type chambers indicate good agreement between
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9 measurements and simulations, however long-term chamber response stability remains an issue
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11 preventing the use of parallel plate type chambers for absorbed dose determination (Muir *et al.*,
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13 2012). Our work shows a small $k_{\bar{B}}$ correction factor measured for the Roos chambers. Use of the Roos
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15 425 chambers to measure the absorbed dose on a parallel MRL would require either more frequent
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17 primary standard lab calibrations or a cross-calibration against a reference dosimeter on a
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19 conventional linac prior to absorbed dose determination on the parallel MRI-linac.
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24 Measurement of the small correction factor for a parallel-plate chamber is important for future MRI-
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26 proton machines where a parallel orientation between the proton beam and magnetic field could be
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28 430 advantageous (Oborn *et al.*, 2017) and parallel plate chambers are a recommended dosimeter for
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30 absorbed dose determination (Andreo *et al.*, 2001).
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33 **Conclusion**

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35 This work presented measurements of the magnetic field correction factor, $k_{\bar{B}}$, for three Roos
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37 chambers at 1 T on a parallel MRI-linac. The measured $k_{\bar{B}}$ relied on the transfer of the dose to water
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39 435 calibration coefficient at both 0 T and 1 T from a calibrated chamber with a known $k_{\bar{B}}$. The
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41 methodology was validated by measuring the $k_{\bar{B}}$ for a PTW Farmer chamber and comparing to
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43 published simulations in the literature. The $k_{\bar{B}}$ for the PTW Farmer chamber at 1 T on a parallel MRI-
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45 linac was 0.993 ± 0.013 ($k = 1$). The average $k_{\bar{B}}$ factor measured for the three Roos chambers on a 1 T
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47 parallel MRI-linac was 0.999 ± 0.014 ($k = 1$). The beam quality used for the measurements of $k_{\bar{B}}$ was
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49 440 $TPR_{20/10} = 0.632$. The small correction factor for the Roos chamber indicates that parallel plate type
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51 chambers are a suitable option for calibration of parallel MRI-linacs. The results have demonstrated a
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53 robust method for measuring magnetic field correction factors on a parallel MRI-linac.
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60 **Acknowledgement**

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Appendix 1: Details on $N_{D,w}$ Transfer Uncertainty

Appendix Table 1: Combined relative standard uncertainty of the $N_{D,w}$ transfer at both 0 T and 1 T for the PTW Farmer and Roos chambers.

Component of Uncertainty	PTW Farmer		Roos	
	0 T	1 T	0 T	1 T
<i>Type A</i>				
Reproducibility of measured charge for reference chamber ¹	0.04	0.04	0.04	0.04
Reproducibility of measured charge for field chamber ¹	0.05	0.05	0.06	0.06
<i>Type B</i>				
Uncertainty in $N_{D,w,Q}^{Ref}$ for reference chamber at beam quality Q	0.7 [#]	1.0 ^{&}	0.7 [#]	1.0 ^{&}
Positioning of reference chamber at correct depth ²	0.1	0.1	0.1	0.1
Positioning of field chamber at correct depth ²	0.1	0.1	0.1	0.1
Water tank setup (± 1 mm) ³	0.1	0.1	0.1	0.1
Stability of reference chamber over time ⁴	0.3	0.3	0.3	0.3
$k_{T,P}$ correction ⁵	0.05	0.05	0.05	0.05
k_{pol} - reference chamber ⁶	0.05	0.05	0.05	0.05
k_s - reference chamber ⁶	0.1	0.1	0.1	0.1
k_{pol} - field chamber ⁶	0.05	0.05	0.05	0.05
k_s - field chamber ⁶	0.1	0.1	0.1	0.1
k_{rp} - Radial Profile or Volume Averaging Difference ⁷	0	0	0.2	0.2
k_{leak} - leakage current	0.05	0.05	0.01	0.01
Combined Relative Standard Uncertainty ($k = 1$)	0.8 %	1.1 %	0.83 %	1.1 %

- 540 1. Reproducibility of the reference chamber (FC65-G) and field chambers (PTW30013 and 3 x Roos chambers) was assessed via the maximum percentage uncertainty observed over three separate measurements (StdDev/Mean for each measurement) at each magnetic field strength. The value combines the uncertainty in the chambers and a CC13 reference chamber. The cc13 chamber was used to address output stability of the linac.
- 545 2. Depth uncertainty was a combination of wall thickness measurement, depth position tool length, depth position set-up reproducibility and chamber cap thickness (0.1 %, <0.1 %, 0.2 % and 0.06 % respectively). Wall thickness, depth position tool length and cap thickness uncertainty was the smallest increment of a vernier calliper. Combined uncertainty equals 0.23 % which at 100 mm depth is 0.23 mm. At a depth of 100 mm on the AusMRL the PDD gradient is 0.4 %/mm. Therefore an uncertainty of 0.23 mm translates to an uncertainty of 0.1 %.
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3. SSD of tank set-up is ± 1 mm. At SSD of 1732 mm, inv sqr law for 1 mm is 0.1 %. Tank set-up not changed between different chambers therefore uncertainty only included once in $N_{D,w}$ Transfer uncertainty.
 4. Stability of the chamber over time was assessed via Strontium 90 checks. Long term stability of chamber response was 0.3 %. AAPM TG51 (Almond *et al.*, 1999) recommends using Co60 not strontium 90. However, that is not available. Applied to both 0 T and 1 T measurements as each $N_{D,w}$ transfer has an uncertainty due to the stability of the chamber.
 5. Chambers were kept in the water phantom for the duration of the measurements to ensure thermal equilibrium with the water. Only resolution uncertainties in the thermometer (Resolution = 0.1°C therefore $\pm 0.05^\circ\text{C}$) and barometer (Resolution = 0.1 kPa therefore ± 0.05 kPa) where included as the same thermometer and barometer were used at 0 T and 1 T for $N_{D,w}$ transfer measurements and thus calibration uncertainties will cancel out. The uncertainties of $\pm 0.05^\circ\text{C}$ and ± 0.05 kPa corresponded to 0.02 % and 0.05 % respectively. Combined in quadrature this becomes 0.05 %.
 6. k_{pol} and k_s uncertainty based on AAPM TG51 (Almond *et al.*, 1999) addendum values.
 7. Volume averaging difference not applicable between Farmer-type chambers as Farmer-type chambers were placed in the same location. Between Farmer-type and Roos chamber the largest difference in calculated k_{vol} was 0.2 %. This was due to the FFF beam being at an extended distance and the dose deposition curve was relatively flat. An estimation of the uncertainty of 0.2 % is used.
 8. Leakage current was corrected for at electrometer with leakage less than 0.1 % of signal. Therefore associated uncertainty was set at 0.05 % as per AAPM TG51 (Almond *et al.*, 1999) addendum for cylindrical chambers and 0.01 % for plane parallel chambers as per Muir *et al.* (Muir *et al.*, 2012)
- # From NPL FFF Calibration report for farmer chambers ($k = 1$)
& From NPL Internal Report 46 (Billas *et al.*, 2018)